



UNIVERSITY OF JYVÄSKYLÄ



UNIVERSITY OF TRENTO - Italy

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A new stable surface in the Heisenberg group

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Introduction

The Heisenberg group, \mathbb{H} : three dimensional, simply connected, nilpotent, non-Abelian Lie group. In exponential coordinates, we identify $\mathbb{H} = \mathbb{R}^3$.

▶ **Group operation**

$$(a, b, c) * (x, y, z) = \left(a + x, b + y, c + z + \frac{1}{2}(ay - bx) \right),$$

▶ **Left-invariant vector fields**

$$X(x, y, z) = \partial_x - \frac{1}{2}y\partial_z$$

$$Y(x, y, z) = \partial_y + \frac{1}{2}x\partial_z$$

$$Z(x, y, z) = \partial_z,$$

Introduction

- ▶ **Intrinsic graph** of $f : \mathbb{R}^2 \rightarrow \mathbb{R}$:

$$\begin{aligned}\Gamma_f &= \{(0, \eta, \tau) * (f(\eta, \tau), 0, 0) : (\eta, \tau) \in \mathbb{R}^2\} \\ &= \left\{ \left(f, \eta, \tau - \frac{1}{2}\eta f \right) : (\eta, \tau) \in \mathbb{R}^2 \right\},\end{aligned}$$

- ▶ **Intrinsic derivative** of f

$$\nabla^f f = \partial_\eta f + f \partial_\tau f,$$

which describes the tangent space of Γ_f ,

- ▶ \mathcal{C}_W^1 is the set of all **C^1 -intrinsic functions**, i.e., $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ such that both f and $\nabla^f f$ are continuous.
- ▶ **Intrinsic area** of Γ_f over $\omega \subset \mathbb{R}^2$

$$\int_\omega \sqrt{1 + (\nabla^f f)^2} \, d\eta \, d\tau.$$

Introduction

Remarks

- ▶ There is a natural notion of **subRiemannian perimeter** for subsets $E \subset \mathbb{H}$. If E has locally finite perimeter, then its reduced boundary $\partial^* E$ is “essentially” the intrinsic graph of a C^1 -intrinsic function.

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- ▶ There are C^1 -intrinsic functions $f \in \mathcal{C}_{\mathbb{W}}^1$ whose intrinsic graph Γ_f is a fractal in \mathbb{R}^3 .

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- ▶ There are C^1 -intrinsic functions $f \in \mathcal{C}_{\mathbb{W}}^1$ whose intrinsic graph Γ_f is a fractal in \mathbb{R}^3 .
- ▶ The set $\mathcal{C}_{\mathbb{W}}^1$ is NOT a vector space. Indeed,

$$f \in \mathcal{C}_{\mathbb{W}}^1 \not\Rightarrow f + 1 \in BV_{intrinsic,loc}$$

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- ▶ The set $\mathcal{C}_{\mathbb{W}}^1$ is NOT a vector space. Indeed,

$$f \in \mathcal{C}_{\mathbb{W}}^1 \not\Rightarrow f + 1 \in BV_{intrinsic,loc}$$

- ▶ By **minimal surface** in \mathbb{H} we mean a topological surface that minimizes the area among all its bounded variations.

The problem

Bernstein's Problem: *Under which conditions on f is the following sentence true?*

If Γ_f is a minimal surface in \mathbb{H} , then Γ_f is a vertical plane.

We are interested in this problem because we want to better understand the space \mathcal{C}_w^1 and the theory of perimeters in \mathbb{H} .

- ▶ If $f \in \mathcal{C}^1(\mathbb{R}^2)$, then it's true!¹
- ▶ If $f \in \mathcal{C}^0(\mathbb{R}^2)$ (even Lipschitz intrinsic), then it's false!²

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- ▶ **What if $f \in \mathcal{C}_{\mathbb{W}}^1$?**

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The problem

Variational approach: if Γ_f is a minimal surface, then, for all $\psi \in \mathcal{C}_c^\infty(\omega)$, the following two conditions are satisfied:

1. $I_f(\psi) = \frac{d}{d\epsilon} \int_\omega \sqrt{1 + (\nabla^{f+\epsilon\psi}(f + \epsilon\psi))^2} d\eta d\tau \Big|_{\epsilon=0} = 0$
2. $II_f(\psi) = \frac{d^2}{d\epsilon^2} \int_\omega \sqrt{1 + (\nabla^{f+\epsilon\psi}(f + \epsilon\psi))^2} d\eta d\tau \Big|_{\epsilon=0} \geq 0$

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This approach cannot work in general: If we only assume $f \in \mathcal{C}_{\mathbb{W}}^1$, then it is **not true** that the graph of the function $f + \epsilon\psi$ has necessarily locally finite area! Indeed,

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But this is another story...

We decided tackle the following problem:

If $f \in W_{loc}^{1,1}(\mathbb{R}^2) \cap \mathcal{C}_{\mathbb{W}}^1$ and Γ_f is a minimal surface in \mathbb{H} , then Γ_f is a vertical plane.

First Variation

For $f \in W_{loc}^{1,1}(\mathbb{R}^2) \cap \mathcal{C}_W^1$ and $\psi \in \mathcal{C}_c^\infty(\mathbb{R}^2)$,

$$I_f(\psi) = \int_{\mathbb{R}^2} \frac{\nabla f f}{\sqrt{1 + (\nabla f f)^2}} (\partial_\eta \psi + \partial_\tau(f\psi)) \, d\eta \, d\tau.$$

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If $f \in \mathcal{C}^2(\mathbb{R}^2)$, then

$$I_f(\psi) = - \int_{\mathbb{R}^2} \nabla^f \left(\frac{\nabla^f f}{\sqrt{1 + (\nabla^f f)^2}} \right) \psi \, d\eta \, d\tau.$$

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Thus, $I_f = 0$ if and only if

$$\nabla^f \nabla^f f = 0.$$

This is a second order differential equation.

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Thus, $I_f = 0$ if and only if

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This is a second order differential equation. However, we can interpret it as (*Lagrangian interpretation*)

$\nabla^f f$ is constant along the integral curves of the vector field

$$\nabla^f = \partial_\eta + f \partial_\tau.$$

First Variation

Conjecture

If $f \in W_{loc}^{1,1} \cap \mathcal{C}_{\mathbb{W}}^1$ and $I_f = 0$, then $\nabla^f f$ is constant along the integral lines of ∇^f , i.e., $\nabla^f \nabla^f f = 0$.

We are working on it.

However, we know that, *if $f \in W_{loc}^{1,1} \cap \mathcal{C}_{\mathbb{W}}^1$ and $\nabla^f f$ is constant along the integral lines of ∇^f , i.e., $\nabla^f \nabla^f f = 0$, then $I_f = 0$.*

$$\nabla^f \nabla^f f = 0$$

$$\nabla^f = \partial_\eta + f \partial_\tau$$

Lemma

Let $f \in \mathcal{C}_{\mathbb{W}}^1$. $\nabla^f f$ is constant along the integral curves of ∇^f if and only if there are continuous functions $A, B : \mathbb{R} \rightarrow \mathbb{R}$ such that

1. all the integral curves of ∇^f are given by $t \mapsto (t, g(t, \zeta))$, where

$$g(t, \zeta) = \frac{A(\zeta)}{2} t^2 + B(\zeta) t + \zeta;$$

$$\nabla^f \nabla^f f = 0$$

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Lemma

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3. $f(t, g(t, \zeta)) = \partial_t g(t, z) = A(\zeta) t + B(\zeta)$;
4. $\nabla^f f(t, g(t, \zeta)) = \partial_t^2 g(t, z) = A(\zeta)$.

$$\nabla^f \nabla^f f = 0$$

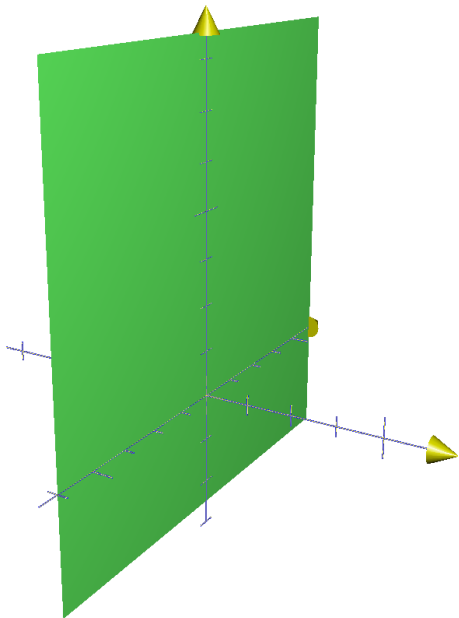
Consider the case ($B = 0$, $A : \mathbb{R} \rightarrow \mathbb{R}$ non-decreasing and continuous)

$$f \left(t, A(\zeta) \frac{t^2}{2} + \zeta \right) = A(\zeta)t.$$

We may construct the intrinsic graph of f in this way:

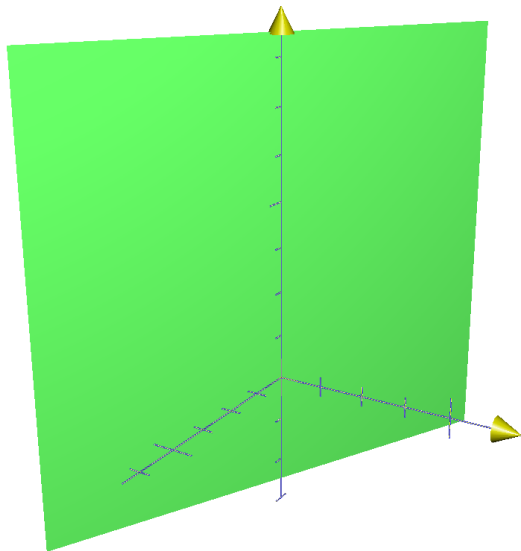
$$\Gamma_f = \{(0, 0, \zeta) + t(A(\zeta), 1, 0) : t, \zeta \in \mathbb{R}\}$$

$\nabla^f \nabla^f f = 0$: Examples



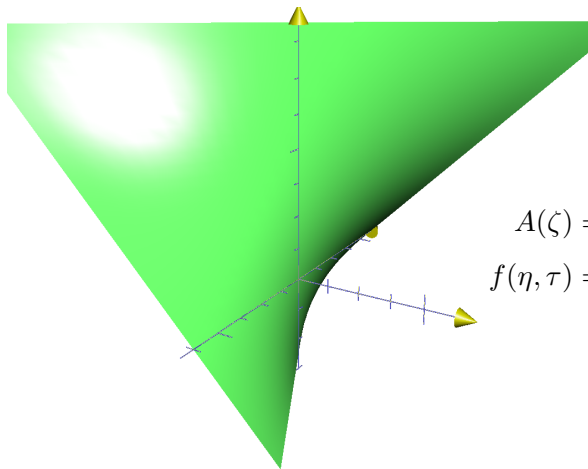
$$A(\zeta) = 0$$
$$f(\eta, \tau) = 0$$

$\nabla^f \nabla^f f = 0$: Examples



$$A(\zeta) = 1$$
$$f(\eta, \tau) = \eta$$

$\nabla^f \nabla^f f = 0$: Examples



$$A(\zeta) = \zeta$$
$$f(\eta, \tau) = \frac{\eta}{\eta^2/2 + 1}$$

Second Variation

For $f \in W_{loc}^{1,1}(\mathbb{R}^2) \cap \mathcal{C}_{\mathbb{W}}^1$ and $\psi \in \mathcal{C}_c^\infty(\mathbb{R}^2)$,

$$II_f(\psi) = \int_{\mathbb{R}^2} \frac{(\partial_\eta \psi + f \partial_\tau \psi + \psi \partial_\tau f)^2}{(1 + (\nabla^f f)^2)^{3/2}} + \frac{\partial_\tau(\psi^2) \nabla^f f}{(1 + (\nabla^f f)^2)^{1/2}} d\eta d\tau$$

Let's assume that f satisfies $\nabla^f \nabla^f f = 0$, with $A, B \in \mathcal{C}(\mathbb{R})$.

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Proposition

If A (and B) is absolutely continuous, then

1. $f \in W_{loc}^{1,1}(\mathbb{R}^2) \cap \mathcal{C}_{\mathbb{W}}^1$;
2. $I_f = 0$;
3. if $II_f \geq 0$, then $A' = B = 0$ and thus Γ_f is a vertical plane.

A new stable surface

Theorem

Take $B = 0$ and

$$A(\zeta) = \begin{cases} 0 & \zeta \leq 0 \\ \text{Cantor function} & 0 \leq \zeta \leq 1 \\ 1 & \zeta \geq 1 \end{cases}$$

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Then

1. $f \in W_{loc}^{1,2}(\mathbb{R}^2) \cap \mathcal{C}_{\mathbb{W}}^1$;

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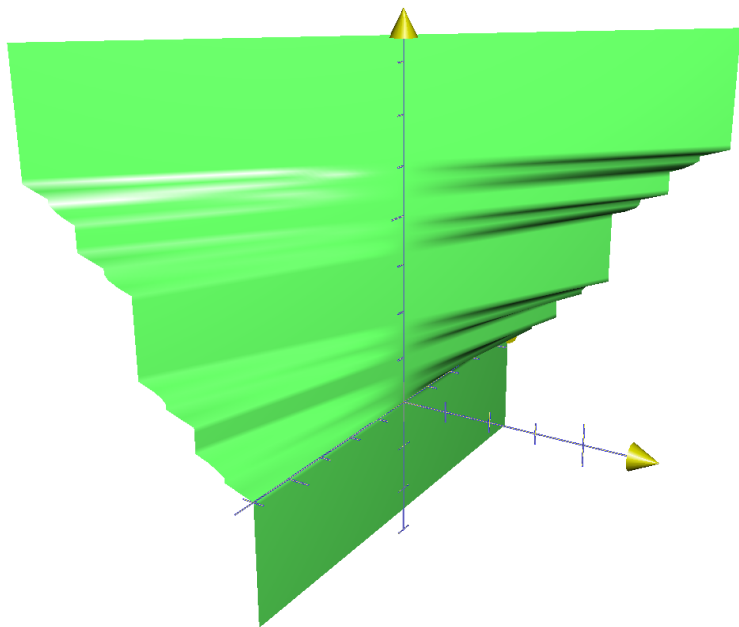
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However, we still don't know the answer to the question

Is Γ_f a minimal surface?

A new stable surface



Thank you for your attention!